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RCX:	The	Robot's	<b>Brain</b>

**Foreword** 

■ The RCX is a microcomputer than interfaces with input and output devices. Programs can be written on a PC and then downloaded to

the unit through the IR

■ The RCX uses two types of memory: read-only memory (ROM) and modifiable random access memory (RAM).

tower.

■ The RCX can be expanded in two ways: using a different programming software like NQC or the Java APIs, or replacing the default firmware with a new one.

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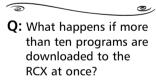
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## Create Custom Components



- **A:** The 11th (and further) programs will appear in the program list, represented using blanks.
- **Q:** What if I have a LEGO tower connected to the USB port?
- A: Set the RCXTTY environment variable to the value USB, instead of to a serial port value.

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### Debugging leJOS Programs

- The best way to debug a leJOS program is to use the Sound and LCD classes in unison to provide you with feedback of the robot's state.
- Normal Java exception handling applies to leJOS, allowing you to separate code for normal operation and code for error situations.

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Using the leJOS Visual Interface

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A RCX Jini Server

A RCX Jini Client

Overview of	 n

Jini is a Java tech-
nology built on top of
RMI, enabling clients
and services to interact
in a network with little
administrative over-
head.

- One feature of Jini is that it is vary applicable to embedded devices, including devices like the RCX.
- The Jini Technology Starter Kit (TSK) includes all of the required jar files as well as some service implementations such as reggie, an implementation of a lookup service.

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