

Contents

<i>Preface</i>	<i>ix</i>		
Part 1 Statics and strength of materials	1		
1 The effects of forces on materials	1		
1.1 Introduction	1	4.2 Worked problems on mechanisms and pin-jointed trusses	41
1.2 Tensile force	2	4.3 Graphical method	42
1.3 Compressive force	2	4.4 Method of joints (a mathematical method)	46
1.4 Shear force	2	4.5 The method of sections (a mathematical method)	52
1.5 Stress	2	Assignment 1	55
1.6 Strain	3		
1.7 Elasticity, limit of proportionality and elastic limit	6	5 Simply supported beams	57
1.8 Hooke's law	7	5.1 The moment of a force	57
1.9 Ductility, brittleness and malleability	11	5.2 Equilibrium and the principle of moments	58
1.10 Modulus of rigidity	12	5.3 Simply supported beams having point loads	61
1.11 Thermal strain	12	5.4 Simply supported beams with couples	64
1.12 Compound bars	13		
2 Tensile testing	18	6 Bending moment and shear force diagrams	69
2.1 The tensile test	18	6.1 Introduction	69
2.2 Worked problems on tensile testing	19	6.2 Bending moment (M)	69
2.3 Further worked problems on tensile testing	21	6.3 Shearing force (F)	69
		6.4 Worked problems on bending moment and shearing force diagrams	70
3 Forces acting at a point	25	6.5 Uniformly distributed loads	78
3.1 Scalar and vector quantities	25		
3.2 Centre of gravity and equilibrium	25	7 First and second moment of areas	84
3.3 Forces	26	7.1 Centroids	84
3.4 The resultant of two coplanar forces	27	7.2 The first moment of area	84
3.5 Triangle of forces method	28	7.3 Centroid of area between a curve and the x -axis	84
3.6 The parallelogram of forces method	29	7.4 Centroid of area between a curve and the y -axis	85
3.7 Resultant of coplanar forces by calculation	29	7.5 Worked problems on centroids of simple shapes	86
3.8 Resultant of more than two coplanar forces	30	7.6 Further worked problems on centroids of simple shapes	87
3.9 Coplanar forces in equilibrium	32	7.7 Second moments of area of regular sections	88
3.10 Resolution of forces	34	7.8 Second moment of area for 'built-up' sections	96
3.11 Summary	37	Assignment 2	102
4 Forces in structures	40		
4.1 Introduction	40		

8 Bending of beams	103	15 Friction	170
8.1 Introduction	103	15.1 Introduction to friction	170
8.2 To prove that $\frac{\sigma}{y} = \frac{M}{I} = \frac{E}{R}$	103	15.2 Coefficient of friction	170
8.3 Worked problems on the bending of beams	105	15.3 Applications of friction	172
9 Torque	109	15.4 Friction on an inclined plane	173
9.1 Couple and torque	109	15.5 Motion up a plane with the pulling force P parallel to the plane	173
9.2 Work done and power transmitted by a constant torque	110	15.6 Motion down a plane with the pulling force P parallel to the plane	174
9.3 Kinetic energy and moment of inertia	112	15.7 Motion up a plane due to a horizontal force P	175
9.4 Power transmission and efficiency	116	15.8 The efficiency of a screw jack	177
10 Twisting of shafts	120	16 Motion in a circle	182
10.1 Introduction	120	16.1 Introduction	182
10.2 To prove that $\frac{\tau}{r} = \frac{T}{J} = \frac{G\theta}{L}$	120	16.2 Motion on a curved banked track	184
10.3 Worked problems on the twisting of shafts	122	16.3 Conical pendulum	185
Assignment 3	126	16.4 Motion in a vertical circle	187
Part 2 Dynamics	127	16.5 Centrifugal clutch	189
11 Linear and angular motion	127	17 Simple harmonic motion	191
11.1 The radian	127	17.1 Introduction	191
11.2 Linear and angular velocity	127	17.2 Simple harmonic motion (SHM)	191
11.3 Linear and angular acceleration	129	17.3 The spring-mass system	192
11.4 Further equations of motion	130	17.4 The simple pendulum	194
11.5 Relative velocity	132	17.5 The compound pendulum	195
12 Linear momentum and impulse	136	17.6 Torsional vibrations	196
12.1 Linear momentum	136	18 Simple machines	198
12.2 Impulse and impulsive forces	139	18.1 Machines	198
13 Force, mass and acceleration	144	18.2 Force ratio, movement ratio and efficiency	198
13.1 Introduction	144	18.3 Pulleys	200
13.2 Newton's laws of motion	144	18.4 The screw-jack	202
13.3 Centripetal acceleration	147	18.5 Gear trains	203
13.4 Rotation of a rigid body about a fixed axis	149	18.6 Levers	205
13.5 Moment of inertia (I)	149	Assignment 5	209
14 Work, energy and power	153	Part 3 Heat transfer and fluid mechanics	211
14.1 Work	153	19 Heat energy and transfer	211
14.2 Energy	157	19.1 Introduction	211
14.3 Power	159	19.2 The measurement of temperature	212
14.4 Potential and kinetic energy	162	19.3 Specific heat capacity	212
14.5 Kinetic energy of rotation	165	19.4 Change of state	214
Assignment 4	169	19.5 Latent heats of fusion and vaporisation	215
		19.6 A simple refrigerator	217
		19.7 Conduction, convection and radiation	217
		19.8 Vacuum flask	218

19.9	Use of insulation in conserving fuel	218	22.10	Float and tapered-tube meter	251
20	Thermal expansion	221	22.11	Electromagnetic flowmeter	252
20.1	Introduction	221	22.12	Hot-wire anemometer	253
20.2	Practical applications of thermal expansion	221	22.13	Choice of flowmeter	253
20.3	Expansion and contraction of water	222	22.14	Equation of continuity	253
20.4	Coefficient of linear expansion	222	22.15	Bernoulli's Equation	254
20.5	Coefficient of superficial expansion	224	22.16	Impact of a jet on a stationary plate	255
20.6	Coefficient of cubic expansion	225	23	Ideal gas laws	258
	Assignment 6	229	23.1	Introduction	258
21	Hydrostatics	230	23.2	Boyle's law	258
21.1	Pressure	230	23.3	Charles' law	259
21.2	Fluid pressure	231	23.4	The pressure law	260
21.3	Atmospheric pressure	232	23.5	Dalton's law of partial pressure	260
21.4	Archimedes' principle	233	23.6	Characteristic gas equation	261
21.5	Measurement of pressure	235	23.7	Worked problems on the characteristic gas equation	261
21.6	Barometers	235	23.8	Further worked problems on the characteristic gas equation	263
21.7	Absolute and gauge pressure	237	24	The measurement of temperature	267
21.8	The manometer	237	24.1	Introduction	267
21.9	The Bourdon pressure gauge	238	24.2	Liquid-in-glass thermometer	267
21.10	Vacuum gauges	239	24.3	Thermocouples	268
21.11	Hydrostatic pressure on submerged surfaces	240	24.4	Resistance thermometers	270
21.12	Hydrostatic thrust on curved surfaces	241	24.5	Thermistors	272
21.13	Buoyancy	241	24.6	Pyrometers	272
21.14	The stability of floating bodies	242	24.7	Temperature indicating paints and crayons	274
22	Fluid flow	247	24.8	Bimetallic thermometers	274
22.1	Introduction	247	24.9	Mercury-in-steel thermometer	274
22.2	Differential pressure flowmeters	247	24.10	Gas thermometers	275
22.3	Orifice plate	247	24.11	Choice of measuring device	275
22.4	Venturi tube	248		Assignment 7	277
22.5	Flow nozzle	249		A list of formulae	279
22.6	Pitot-static tube	249		Greek alphabet	283
22.7	Mechanical flowmeters	250		Answers to multiple-choice questions	284
22.8	Deflecting vane flowmeter	250		Index	287
22.9	Turbine type meters	250			